



ARM IN REST POSITION

FIG. 1A

ARM DEFORMED  
NEGATIVELY USING  
SIX INDIVIDUAL SCALE  
CONTROLS. NOTE  
THAT USING THE  
SINGLE CONTROLS  
CAUSES LOSS OF  
VOLUME IN THE ARM  
AT THE ELBOW.

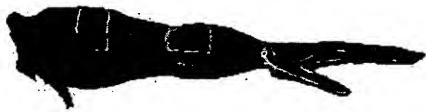


FIG. 1B

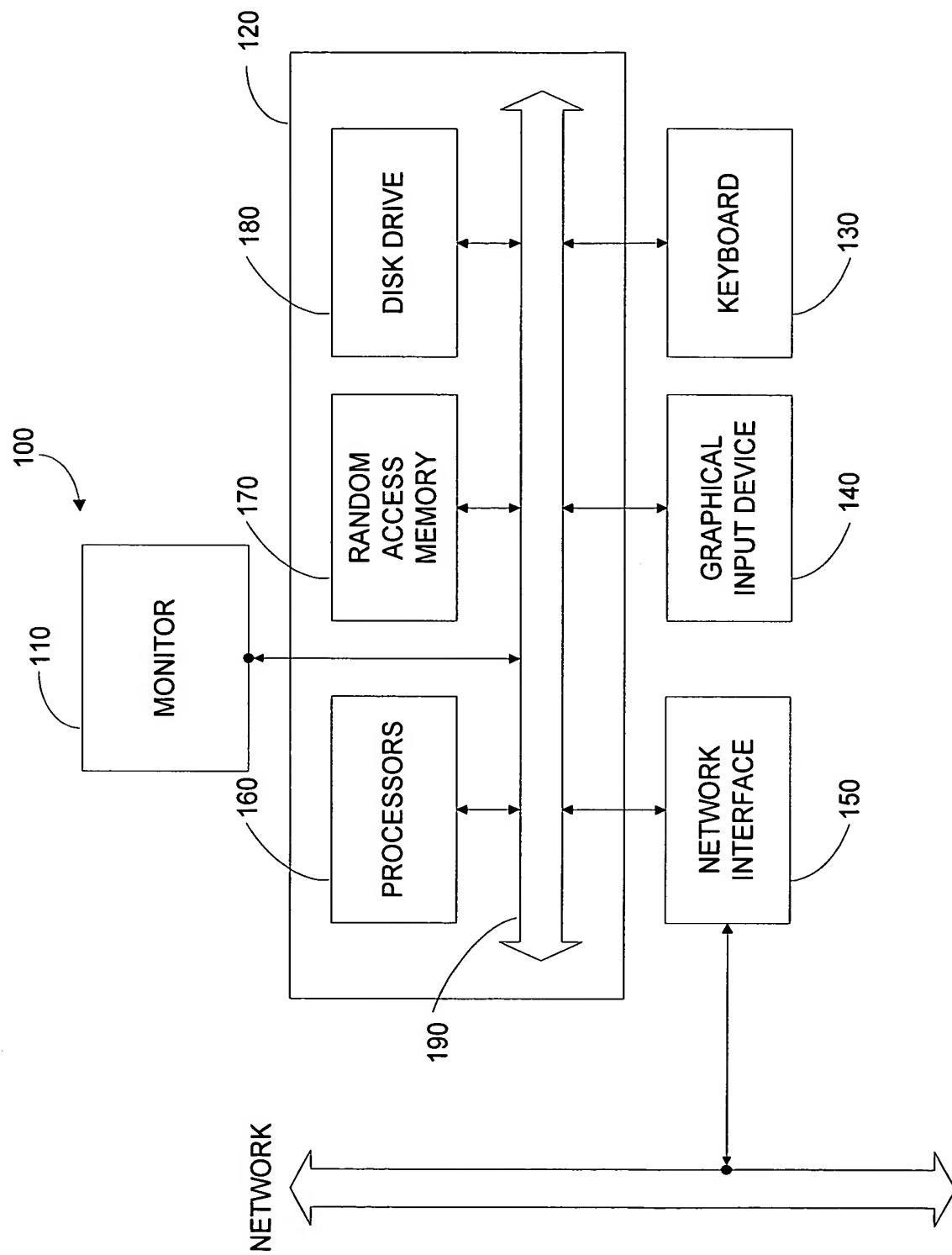
ARM DEFORMED  
POSITIVELY USING SIX  
INDIVIDUAL SCALE  
CONTROLS. NOTE  
THAT USING THE  
SINGLE CONTROLS  
CAUSE LOSS OF  
VOLUME IN THE ARM,  
UNDESIRED BULGING  
AT THE ELBOW.



FIG. 1C

PRIOR ART

FIG. 2



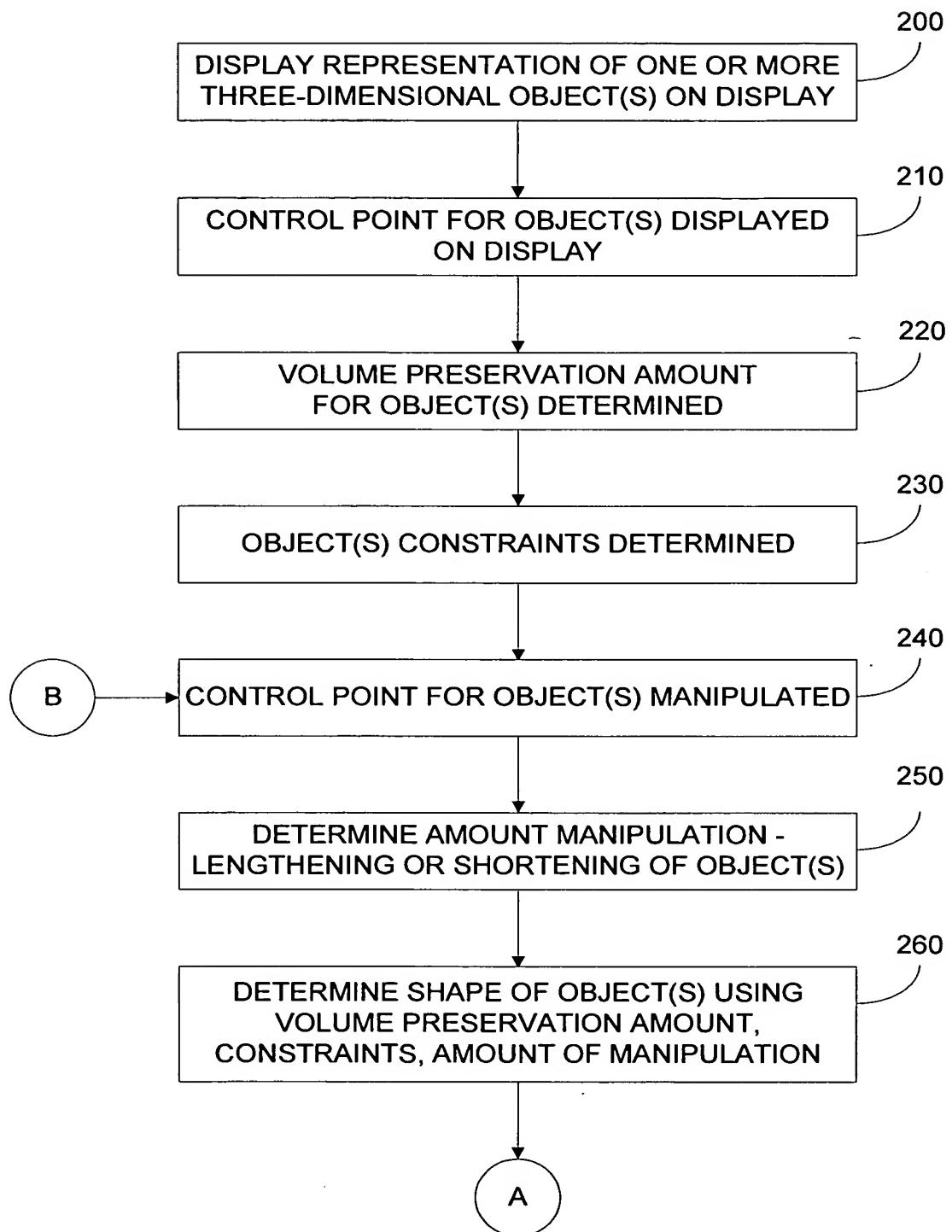


FIG. 3A

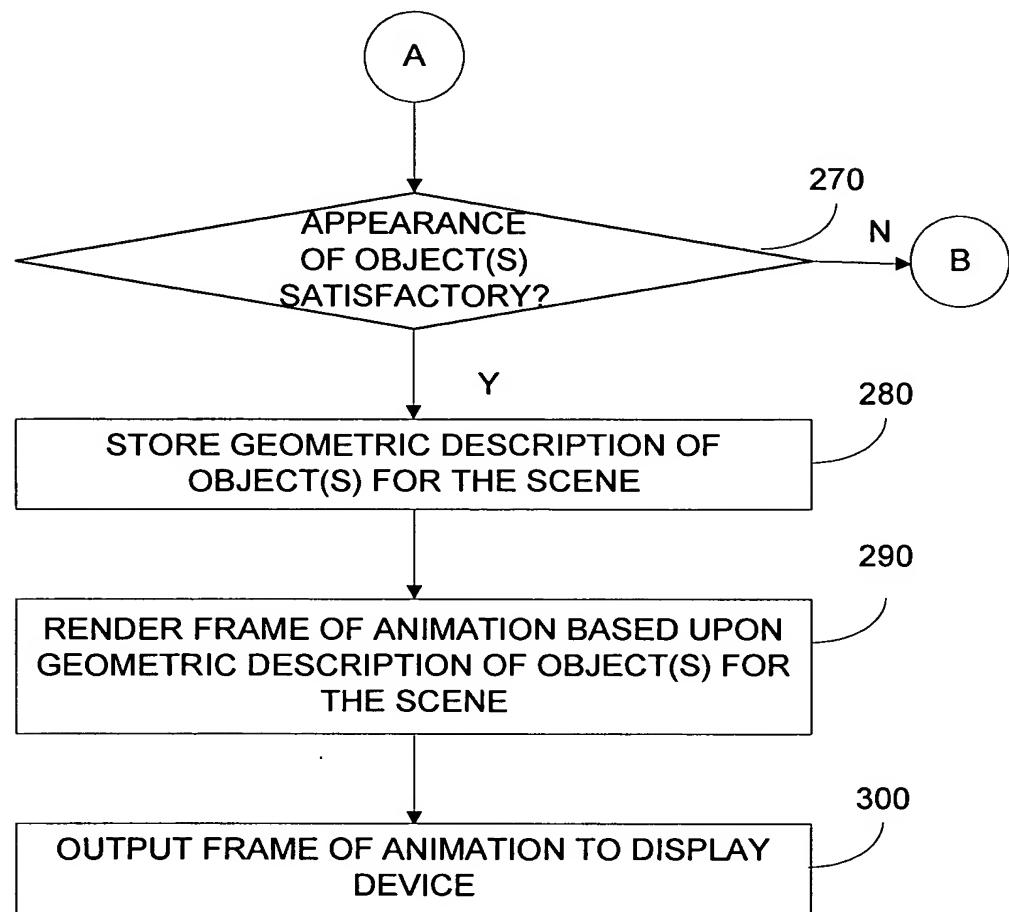


FIG. 3B

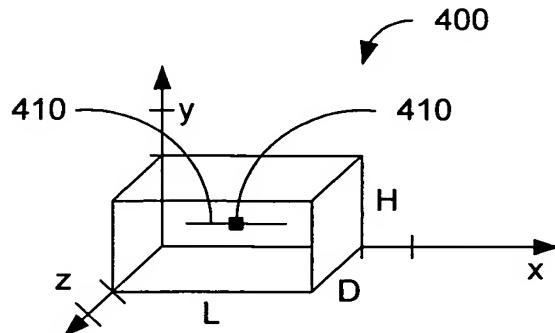


FIG. 4A

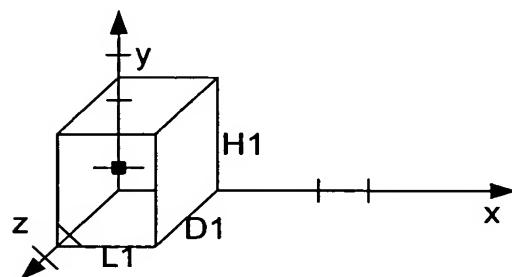


FIG. 4B

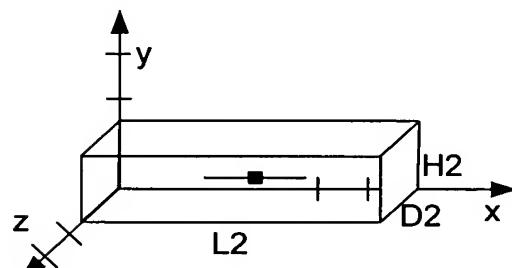


FIG. 4C

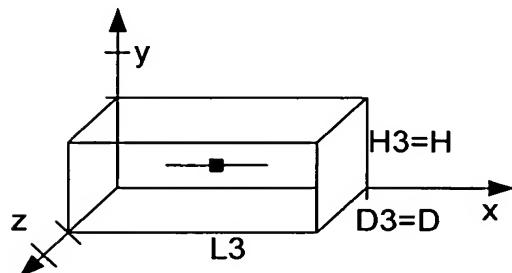


FIG. 4D

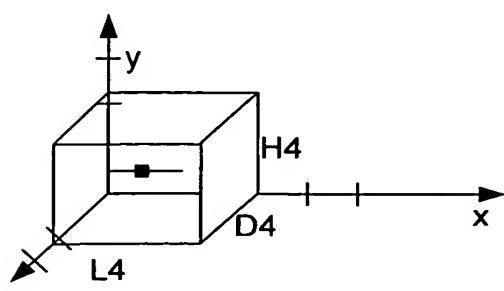


FIG. 4E

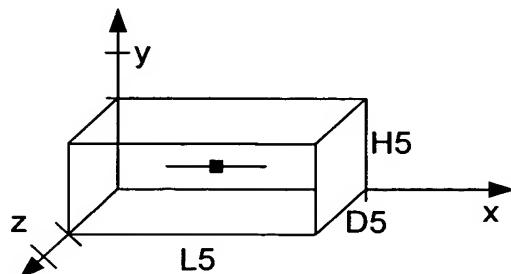


FIG. 4F

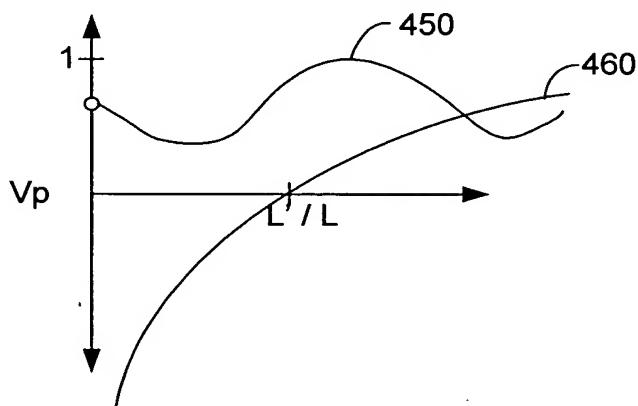


FIG. 4G

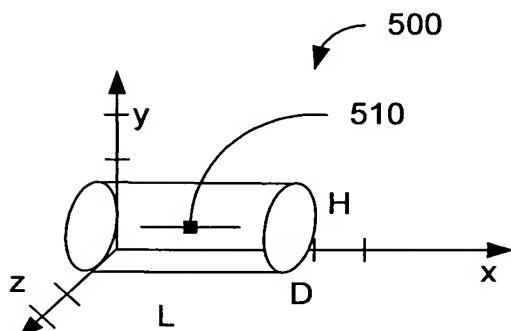


FIG. 5A

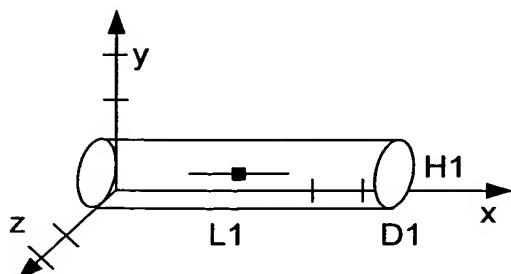


FIG. 5B

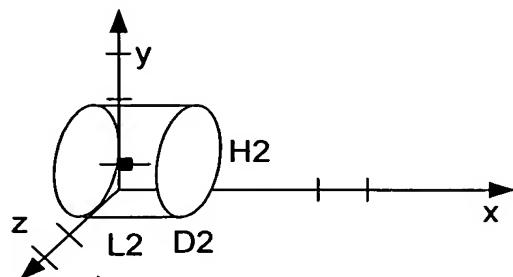


FIG. 5C

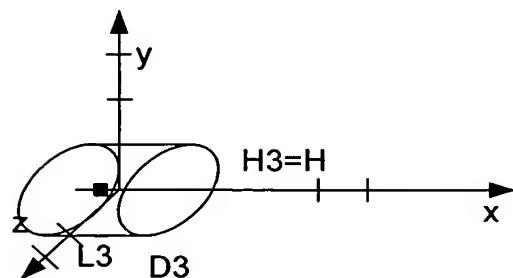


FIG. 5D

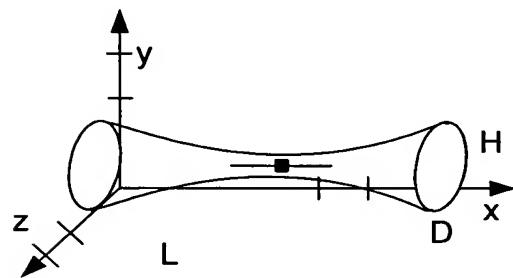


FIG. 5E

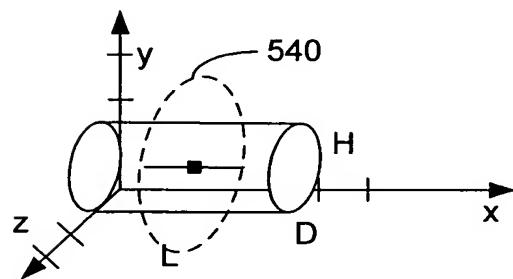


FIG. 5F

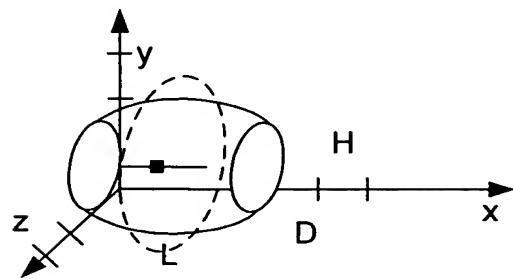


FIG. 5G1

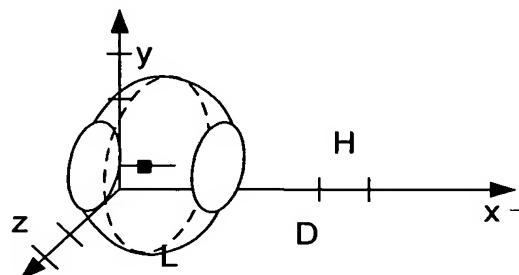


FIG. 5G2

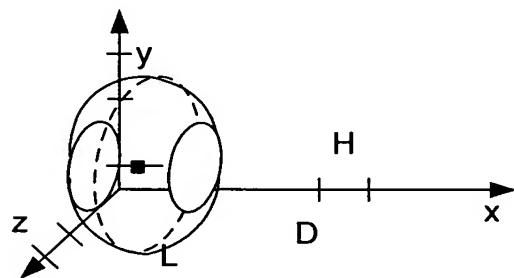


FIG. 5G3

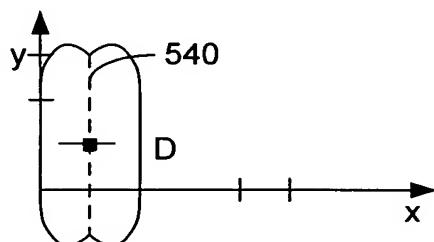


FIG. 5G4

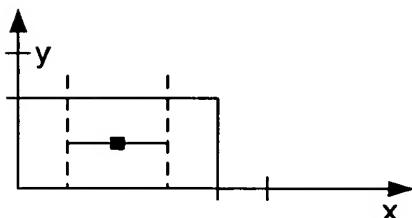
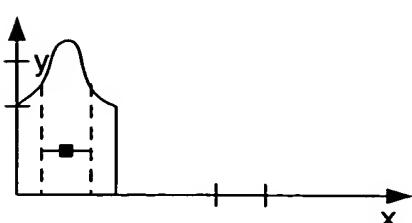
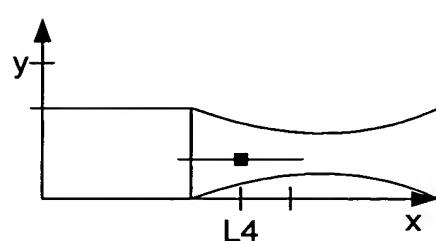
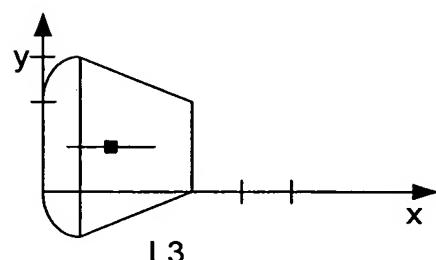
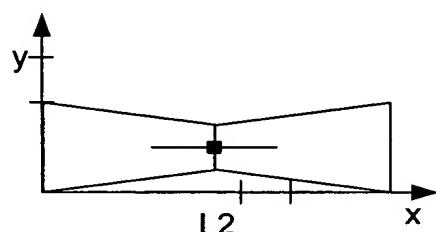
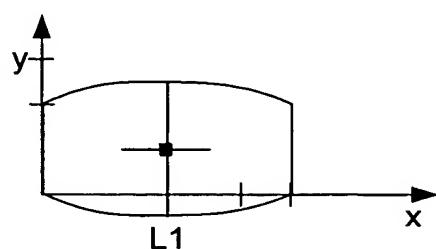
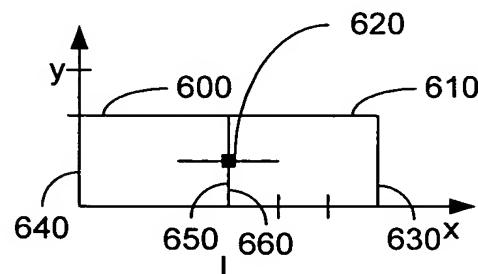
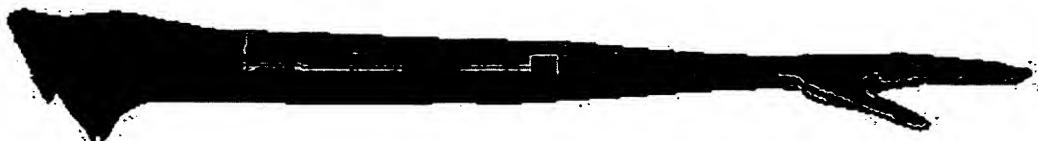


FIG. 5H







ARM AT REST WITH THE SQUASH AND STRETCH WIDGET DISPLAYED. TO MOVE THE ARM, THE ANIMATOR GRABS THE CUBE MANIPULATOR AND DRAGS IT EITHER IN THE POSITIVE OR NEGATIVE DIRECTION TO DEFORM THE ARM

FIG. 7A

ARM DEFORMED WITH SQUASH AND STRETCH WIDGET IN THE NEGATIVE DIRECTION. NOTICE THAT THERE IS VOLUME PRESERVATION ACROSS THE UPPER ARM AND FOREARM.

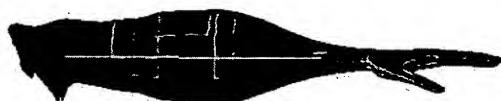


FIG. 7B

ARM DEFORMED WITH SQUASH AND STRETCH WIDGET IN THE POSITIVE DIRECTION. NOTICE THE SMOOTH TRANSITION BETWEEN THE UPPER ARM AND LOWER ARM.



FIG. 7C